

SOME CURVATURE RESULTS ON KENMOTSU METRIC SPACES

Pakize Uygun, Süleyman Dirik, and Mehmet Atçeken

ABSTRACT. In this paper we present the curvature tensors of Kenmotsu manifold satisfying the conditions $R(X, Y) \cdot W_0 = 0$, $R(X, Y) \cdot W_1^* = 0$, $R(X, Y) \cdot W_1 = 0$, $R(X, Y) \cdot W_3 = 0$ and $R(X, Y) \cdot W_4 = 0$. According these cases, Kenmotsu manifolds have been characterized. I think that some interesting results on a Kenmotsu metric manifold are obtained.

1. Introduction

K.Kobayashi and K. Nomizu shown that any two simply connected complete Riemannian manifolds of constant curvature k are isometric to each other in 1963 [9]. After that Kenmotsu manifolds have been studied by many authors in several ways to a different extent such as [17].

K. Kenmotsu studied a class of contact Riemannian manifolds an call them Kenmotsu manifold [8]. He denote that if a Kenmotsu manifold satisfies the condition $R(X, Y) \cdot R = 0$, where R is the Riemanniann curvature tensor and $R(X, Y)$ denotes the derivation of the tensor algebra at each point of the tangent space.

Subsequent to, K. De and U.C. De obtained conharmonically flat and ϕ -conharmonically flat Kenmotsu manifold and they proved that the manifold is an Einstein manifold and a η -Einstein manifold. They researched a 3- dimensional Kenmotsu manifold admitting a non-null concircular vector field [4].

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The object of this paper is to study properties of the some certain curvature tensor in a Kenmotsu metric manifold. In the present paper we survey $R(X, Y) \cdot W_0 = 0$, $R(X, Y) \cdot W_1^* = 0$, $R(X, Y) \cdot W_1 = 0$, $R(X, Y) \cdot W_3 = 0$ and $R(X, Y) \cdot W_4 = 0$, where W_0 , W_1 , W_1^* , W_3 , and W_4 denote the curvature tensors of a manifold, respectively.

2. Preliminaries

Let M be a $(2n + 1)$ -dimensional connected almost contact metric manifold with an almost contact metric structure (ϕ, ξ, η, g) , that is, ϕ is an $(1, 1)$ tensor field, ξ is a vector field, η is a 1-form and the Riemannian metric g satisfying

$$(2.1) \quad \phi^2(X) = -X + \eta(X)\xi, \quad \eta(\phi X) = 0,$$

$$(2.2) \quad \eta(\xi) = 1, \quad \phi\xi = 0, \quad \eta\phi = 0$$

for all $X, Y \in \chi(M)$ [8]. Let g be Riemannian metric compatible with (ϕ, ξ, η) , that is

$$(2.3) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$$

or equivalently,

$$(2.4) \quad g(X, \phi Y) = -g(\phi X, Y) \quad \text{and} \quad g(X, \xi) = \eta(X)$$

for all $X, Y \in \chi(M)$ [2]. If moreover,

$$(2.5) \quad (\nabla_X \phi)Y = -\eta(Y)\phi X - g(X, \phi Y)\xi,$$

$$(2.6) \quad \nabla_X \xi = X - \eta(X)\xi,$$

where ∇ denotes the Riemannian connection of g hold, then (M, ϕ, ξ, η, g) is called an almost Kenmotsu manifold. An almost Kenmotsu manifold becomes a Kenmotsu manifold if

$$(2.7) \quad g(X, \phi Y) = d\eta(X, Y).$$

In a Kenmotsu manifold M , the following relation holds [8, 5]:

$$(2.8) \quad (\nabla_X \eta)Y = g(X, Y) - \eta(X)\eta(Y),$$

$$(2.9) \quad R(X, Y)\xi = \eta(X)Y - \eta(Y)X,$$

$$(2.10) \quad R(\xi, X)Y = \eta(Y)X - g(X, Y)\xi,$$

$$(2.11) \quad S(X, \xi) = -(n - 1)\eta(X),$$

$$(2.12) \quad Q\xi = -(n - 1)\xi,$$

where R is the Riemannian curvature tensor and S is Ricci tensor defined by $S(X, Y) = g(QX, Y)$, where Q is Ricci operator. It yields to

$$(2.13) \quad S(\phi X, \phi Y) = S(X, Y) + (n - 1)\eta(X)\eta(Y).$$

A Kenmotsu manifold M is said to be an η -Einstein manifold if its Ricci tensor S of the form

$$(2.14) \quad S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y)$$

for arbitrary vector fields X, Y ; where a and b are functions on (M^{2n+1}, g) . If $b = 0$, then η -Einstein manifold becomes Einstein manifold [13, 8].

Let M be an $(2n + 1)$ -dimensional Kenmotsu manifold. The curvature tensor \tilde{R} of M with respect to the connection $\tilde{\nabla}$ is defined by

$$(2.15) \quad \tilde{R}(X, Y)Z = \tilde{\nabla}_X \tilde{\nabla}_Y Z - \tilde{\nabla}_Y \tilde{\nabla}_X Z - \tilde{\nabla}_{[X, Y]}Z.$$

Then, in a Kenmotsu manifold, we have

$$(2.16) \quad \tilde{R}(X, Y)Z = R(X, Y)Z + g(Y, Z)X - g(X, Z)Y,$$

where $R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]}Z$, is the curvature tensor of M with respect to the connection ∇ .

The Ricci tensor \tilde{S} and the scalar curvature \tilde{r} of the Kenmotsu manifold M with respect to the connection $\tilde{\nabla}$ is given by

$$(2.17) \quad \tilde{S}(X, Y) = \sum_{i=1}^n g(\tilde{R}(e_i, X)Y, e_i) = S(X, Y) + (n - 1)g(X, Y)$$

and

$$(2.18) \quad \tilde{r} = \sum_{i=1}^n \tilde{S}(e_i, e_i) = r + n(n - 1),$$

where \tilde{r} and r are the scalar curvatures of the connection $\tilde{\nabla}$ and ∇ , respectively [18, 19, 21].

The concept of W_0 -curvature tensor was defined by [12]. W_0 -curvature tensor, W_1 -curvature tensor, W_1^* -curvature tensor, W_3 -curvature tensor and W_4 -curvature tensor of a $(2n + 1)$ -dimensional Riemannian manifold are, respectively, defined as

$$(2.19) \quad W_0(X, Y)Z = R(X, Y)Z - \frac{1}{2n}[S(Y, Z)X - g(X, Z)QY],$$

$$(2.20) \quad W_1(X, Y)Z = R(X, Y)Z + \frac{1}{2n}[S(Y, Z)X - S(X, Z)Y],$$

$$(2.21) \quad W_1^*(X, Y)Z = R(X, Y)Z - \frac{1}{2n}[S(Y, Z)X - S(X, Z)Y],$$

$$(2.22) \quad W_3(X, Y)Z = R(X, Y)Z - \frac{1}{2n}[S(X, Z)Y - g(Y, Z)QX],$$

$$(2.23) \quad W_4(X, Y)Z = R(X, Y)Z + \frac{1}{2n}[g(X, Z)QY - g(X, Y)QZ],$$

for all $X, Y, Z \in \chi(M)$ [11, 12].

3. Some Curvature Results On Kenmotsu Metric Spaces

In this section, we will give the main results for this paper.

Let M be $(2n+1)$ -dimensional Kenmotsu metric manifold and we denote W_0 curvature tensor from (2.19), we have for later

$$(3.1) \quad W_0(X, Y)\xi = \eta(X)Y - \frac{n+1}{2n}\eta(Y)X + \frac{1}{2n}\eta(X)QY.$$

Putting $X = \xi$, in (3.1)

$$(3.2) \quad W_0(\xi, Y)\xi = Y - \frac{n+1}{2n}\eta(Y)\xi + \frac{1}{2n}QY.$$

In (2.20) choosing $Z = \xi$ and using (2.9), we obtain

$$(3.3) \quad W_1(X, Y)\xi = \frac{3n-1}{2n}(\eta(X)Y - \eta(Y)X).$$

In (3.3), it follows

$$(3.4) \quad W_1(\xi, Y)\xi = \frac{3n-1}{2n}(Y - \eta(Y)\xi).$$

From (2.21) and (2.9), we arrive

$$(3.5) \quad W_1^*(X, Y)\xi = \frac{n+1}{2n}(\eta(X)Y - \eta(Y)X),$$

and

$$(3.6) \quad W_1^*(\xi, Y)\xi = \frac{n+1}{2n}(Y - \eta(Y)\xi).$$

Choosing $Z = \xi$, in (2.22), we obtain

$$(3.7) \quad W_3(X, Y)\xi = \frac{3n-1}{2n}\eta(X)Y - \eta(Y)X + \frac{1}{2n}\eta(Y)QX.$$

In (3.7) it follows

$$(3.8) \quad W_3(\xi, Y)\xi = \frac{3n-1}{2n}(Y - \eta(Y)\xi).$$

In (2.23), choosing $Z = \xi$ and using (2.9), we get

$$(3.9) \quad W_4(X, Y)\xi = \eta(X)Y - \eta(Y)X + \frac{1}{2n}\{\eta(X)QY + (n-1)g(X, Y)\xi\}.$$

Setting $X = \xi$, in (3.9), we arrive

$$(3.10) \quad W_4(\xi, Y)\xi = Y - \frac{n+1}{2n}\eta(Y)\xi + \frac{1}{2n}QY.$$

THEOREM 1. *Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a Kenmotsu manifold. Then M is a W_0 semi-symmetric if and only if M is an Einstein manifold.*

PROOF. Suppose M is a W_0 semi-symmetric. This implies that

$$\begin{aligned} (R(X, Y)W_0)(U, W)Z &= R(X, Y)W_0(U, W)Z - W_0(R(X, Y)U, W)Z \\ &\quad - W_0(U, R(X, Y)W)Z \\ (3.11) \quad &\quad - W_0(U, W)R(X, Y)Z = 0, \end{aligned}$$

for any $X, Y, U, W, Z \in \chi(M)$. Taking $X = Z = \xi$ in (3.11), making use of (3.1), (2.9) and (2.10), for $A = -\frac{n+1}{2n}$, $B = \frac{1}{2n}$, we have

$$\begin{aligned} (R(\xi, Y)W_0)(U, W)\xi &= R(\xi, Y)(\eta(U)W + A\eta(W)U + B\eta(U)QW) \\ &\quad - W_0(\eta(U)Y) - g(Y, U)\xi, W)\xi \\ &\quad - W_0(U, \eta(W)Y - g(Y, W)\xi)\xi \\ (3.12) \quad &\quad - W_0(U, W)(Y - \eta(Y)\xi) = 0. \end{aligned}$$

Taking into account (3.1), (3.2), (2.9) in (3.12), we obtain

$$\begin{aligned} &W_0(U, W)Y + \eta(U)g(Y, W)\xi + B(n-1)\eta(U)\eta(W)Y \\ &+ B\eta(U)S(Y, W)\xi - g(Y, U)W - Bg(Y, U)QW \\ &+ B\eta(U)\eta(W)QY + g(Y, W)U + A\eta(U)g(Y, W)\xi \\ (3.13) \quad &+ Bg(Y, W)QU = 0. \end{aligned}$$

Putting (2.19), (2.4), choosing $W = \xi$ in (3.13), we arrive

$$\begin{aligned} &BS(U, Y)\xi - \eta(Y)U - B\eta(Y)QU + \eta(U)\eta(Y)\xi + B(n-1)\eta(U)Y \\ &- B(n-1)\eta(U)\eta(Y)\xi + B(n-1)g(Y, U)\xi + B\eta(U)QY \\ (3.14) \quad &+ \eta(Y)U + A\eta(U)\eta(Y)\xi + B\eta(Y)QU = 0. \end{aligned}$$

Inner product both sides of (3.14) by $\xi \in \chi(M)$ and using (2.11), we conclude

$$S(U, Y) = (1-n)g(U, Y).$$

So, M is an Einstein manifold. Conversely, let $M^{2n+1}(\phi, \xi, \eta, g)$ be an Einstein manifold i.e. $S(U, Y) = (1-n)g(U, Y)$, then from (3.14), (3.13), (3.12) and (3.11), we have $R(X, Y) \cdot W_0 = 0$. \square

THEOREM 2. *Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a Kenmotsu manifold. Then M is a W_1 semi-symmetric if and only if M is an Einstein manifold.*

PROOF. Suppose that M is a W_1 semi-symmetric. This yields to

$$\begin{aligned} (R(X, Y)W_1)(U, W)Z &= R(X, Y)W_1(U, W)Z - W_1(R(X, Y)U, W)Z \\ &\quad - W_1(U, R(X, Y)W)Z \\ (3.15) \quad &\quad - W_1(U, W)R(X, Y)Z = 0, \end{aligned}$$

for any $X, Y, U, W, Z \in \chi(M)$. Taking $X = Z = \xi$ in (3.15) and using (3.3), (2.9), (2.10), for $A = \frac{3n-1}{2n}$, we obtain

$$\begin{aligned} (R(\xi, Y)W_1)(U, W)\xi &= R(\xi, Y)(A\eta(U)W - A\eta(W)U) \\ &\quad - W_1(\eta(U)Y) - g(Y, U)\xi, W)\xi \\ &\quad - W_1(U, \eta(W)Y - g(Y, W)\xi)\xi \\ (3.16) \quad &\quad - W_1(U, W)(Y - \eta(Y)\xi) = 0. \end{aligned}$$

And we arrive

$$(3.17) \quad \begin{aligned} & A\eta(U)R(\xi, Y)W - A\eta(W)R(\xi, Y)U - \eta(U)W_1(Y, W)\xi \\ & + g(Y, U)W_1(\xi, W)\xi - \eta(W)W_1(U, Y)\xi + g(Y, W)W_1(U, \xi)\xi \\ & - W_1(U, W)Y + \eta(Y)W_1(U, W)\xi = 0. \end{aligned}$$

Taking into account that (2.9), (2.10) and (3.3) in (3.17), we get

$$(3.18) \quad W_1(U, W)Y - Ag(Y, U)W + Ag(Y, W)U = 0.$$

Putting $U = \xi$, using (2.20) in (3.18) and inner product both sides of (3.18) by $\xi \in \chi(M)$, we conclude

$$S(Y, W) = (1 - n)g(Y, W).$$

Thus, M is an Einstein manifold. Conversely, let $M^{2n+1}(\phi, \xi, \eta, g)$ be an Einstein manifold i.e. $S(Y, W) = (1 - n)g(Y, W)$, then from (3.18), (3.17), (3.16) and (3.15), we have $R(X, Y) \cdot W_1 = 0$. \square

THEOREM 3. *Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a Kenmotsu manifold. Then M is a W_1^* semi-symmetric if and only if M is an Einstein manifold.*

PROOF. Suppose that M is a W_1^* semi-symmetric. This yields to

$$(3.19) \quad \begin{aligned} (R(X, Y)W_1^*)(U, W)Z &= R(X, Y)W_1^*(U, W)Z - W_1^*(R(X, Y)U, W)Z \\ &\quad - W_1^*(U, R(X, Y)W)Z \\ &\quad - W_1^*(U, W)R(X, Y)Z = 0, \end{aligned}$$

for any $X, Y, U, W, Z \in \chi(M)$. Taking $X = Z = \xi$ in (3.19) and using (3.5), (2.9), (2.10), for $A = \frac{n+1}{2n}$, we obtain

$$(3.20) \quad \begin{aligned} (R(\xi, Y)W_1^*)(U, W)\xi &= R(\xi, Y)(A\eta(U)W - A\eta(W)U) \\ &\quad - W_1^*(\eta(U)Y - g(Y, U)\xi, W)\xi \\ &\quad - W_1^*(U, \eta(W)Y - g(Y, W)\xi)\xi \\ &\quad - W_1^*(U, W)(Y - \eta(Y)\xi) = 0. \end{aligned}$$

and from (3.20), we arrive

$$(3.21) \quad \begin{aligned} & A\eta(U)R(\xi, Y)W - A\eta(W)R(\xi, Y)U - \eta(U)W_1^*(Y, W)\xi \\ & + g(Y, U)W_1^*(\xi, W)\xi - \eta(W)W_1^*(U, Y)\xi + g(Y, W)W_1^*(U, \xi)\xi \\ & - W_1^*(U, W)Y + \eta(Y)W_1^*(U, W)\xi = 0. \end{aligned}$$

Taking into account that (2.9), (2.10) and (3.5) in (3.21), we get

$$(3.22) \quad W_1^*(U, W)Y - Ag(Y, U)W + Ag(Y, W)U = 0.$$

Setting $U = \xi$ and using (2.11), inner product both sides of (3.22) by $\xi \in \chi(M)$, we have

$$S(Y, W) = (1 - n)g(Y, W).$$

Thus, M is an Einstein manifold. Conversely, let $M^{2n+1}(\phi, \xi, \eta, g)$ be an Einstein manifold i.e. $S(Y, W) = (1 - n)g(Y, W)$, then from (3.22), (3.21), (3.20) and (3.19), we have $R(X, Y) \cdot W_1^* = 0$. \square

THEOREM 4. Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a Kenmotsu manifold. Then M is a W_3 semi-symmetric if and only if M is an Einstein manifold.

PROOF. Suppose that M is a W_3 semi-symmetric. This means that

$$(3.23) \quad \begin{aligned} (R(X, Y)W_3)(U, W, Z) &= R(X, Y)W_3(U, W)Z - W_3(R(X, Y)U, W)Z \\ &\quad - W_3(U, R(X, Y)W)Z \\ &\quad - W_3(U, W)R(X, Y)Z = 0, \end{aligned}$$

for any $X, Y, U, W, Z \in \chi(M)$. Setting $X = Z = \xi$ in (3.23) and making use of (3.7), (2.9), for $A = \frac{3n-1}{2n}$, $B = \frac{1}{2n}$, we obtain

$$(3.24) \quad \begin{aligned} (R(\xi, Y)W_3)(U, W)\xi &= R(\xi, Y)(A\eta(U)W - \eta(W)U + B\eta(W)QU) \\ &\quad - W_3(\eta(U)Y - g(Y, U)\xi, W)\xi \\ &\quad - W_3(U, \eta(W)Y - g(Y, W)\xi)\xi \\ &\quad - W_3(U, W)(Y - \eta(Y)\xi) = 0. \end{aligned}$$

Using (3.7), (3.8), (2.9) in (3.24), we get

$$(3.25) \quad \begin{aligned} &W_3(U, W)Y - \eta(W)g(Y, U)\xi + B(n-1)\eta(W)\eta(U)Y \\ &+ B\eta(W)S(Y, U)\xi + B\eta(W)\eta(U)QY - Ag(Y, U)W \\ &+ A\eta(W)g(U, Y)\xi + Ag(Y, W)U = 0. \end{aligned}$$

Making use of (2.22), choosing $W = \xi$, and inner product both sides of (3.25) by $\xi \in \chi(M)$, we have

$$(3.26) \quad \begin{aligned} &BS(Y, U) - g(Y, U)\xi + B(n-1)\eta(U)Y \\ &+ B\eta(U)QY + Ag(Y, U)\xi = 0. \end{aligned}$$

From (3.26) and by using (2.11), we conclude

$$S(Y, U) = (1-n)g(Y, U).$$

This tell us, M is an Einstein manifold. Conversely, let $M^{2n+1}(\phi, \xi, \eta, g)$ be an Einstein manifold i.e. $S(Y, U) = (1-n)g(Y, U)$, then from (3.26), (3.25), (3.24) and (3.23), we have $R(X, Y) \cdot W_3 = 0$. \square

THEOREM 5. Let $M^{2n+1}(\phi, \xi, \eta, g)$ be a Kenmotsu manifold. Then M is a W_4 semi-symmetric if and only if M is an η -Einstein manifold.

PROOF. Suppose that M is a W_4 semi-symmetric. This means that

$$(3.27) \quad \begin{aligned} (R(X, Y)W_4)(U, W, Z) &= R(X, Y)W_4(U, W)Z - W_4(R(X, Y)U, W)Z \\ &\quad - W_4(U, R(X, Y)W)Z \\ &\quad - W_4(U, W)R(X, Y)Z = 0, \end{aligned}$$

for any $X, Y, U, W, Z \in \chi(M)$. Setting $X = Z = \xi$ in (3.27) and making use of (3.9), (2.9), (2.10), for $A = \frac{1}{2n}$, $B = \frac{n-1}{2n}$, we obtain

$$\begin{aligned}
 (R(\xi, Y)W_4)(U, W)\xi &= R(\xi, Y)(\eta(U)W - \eta(W)U + A\eta(U)QW \\
 &\quad + Bg(U, W)\xi) - W_4(\eta(U)Y - g(Y, U)\xi, W)\xi \\
 &\quad - W_4(U, \eta(W)Y - g(Y, W)\xi)\xi \\
 (3.28) \qquad \qquad \qquad &\quad - W_4(U, W)(Y - \eta(Y)\xi) = 0.
 \end{aligned}$$

Using (3.9) and (3.10) in (3.28), we get

$$\begin{aligned}
 &W_4(U, W)Y + \eta(U)g(Y, W)\xi - \eta(W)g(Y, U)\xi \\
 &+ A(n-1)\eta(U)\eta(W)Y + A\eta(U)S(Y, W)\xi \\
 &+ Bg(U, W)Y + g(Y, U)W + Ag(Y, U)QW \\
 (3.29) \qquad \qquad \qquad &+ A(U)\eta(W)QY + g(Y, W)U + Ag(Y, W)QU = 0.
 \end{aligned}$$

Making use of (2.23) and choosing $U = \xi$ and inner product both sides of in (3.29) by $\xi \in \chi(M)$, we have

$$\begin{aligned}
 &\eta(Y)\eta(W) + g(Y, W) + AS(Y, W) + B\eta(Y)\eta(W) \\
 (3.30) \qquad \qquad \qquad &- A(n-1)\eta(Y)\eta(W) - A(n-1)g(Y, W) = 0.
 \end{aligned}$$

From (3.30) and (2.11), we obtain

$$S(Y, W) = -(n+1)g(Y, W) - 2n\eta(Y)\eta(W).$$

Thus, M is an η -Einstein manifold. Conversely, let $M^{2n+1}(\phi, \xi, \eta, g)$ be an η -Einstein manifold i.e. $S(Y, W) = -(n+1)g(Y, W) - 2n\eta(Y)\eta(W)$, then from (3.30), (3.29), (3.28) and (3.27), we have $R(X, Y) \cdot W_4 = 0$. \square

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PAKIZE UYGUN, DEPARTMENT OF MATHEMATICS, FACULTY OF ARTS AND SCIENCES, TOKAT UNIVERSITY, 60100, TOKAT, TURKEY

Email address: pakizeuygun@hotmail.com

SÜLEYMAN DIRİK, DEPARTMENT OF MATHEMATICS, FACULTY OF ARTS AND SCIENCES, AMASYA UNIVERSITY, 05100, AMASYA, TURKEY

Email address: slymdirik@gmail.com

MEHMET ATEKEN, DEPARTMENT OF MATHEMATICS, FACULTY OF ARTS AND SCIENCES, AKSARAY UNIVERSITY, 68100, AKSARAY, TURKEY

Email address: mehmet.atceken382@gmail.com